IMTS and JIMTOF 2018 Grand Challenge and QIF

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Traditional Inspection Data Flow



Report after three days

Grand Challenge Inspection Data Flow



The Grand Challenge and QIF

- QIF reports on the quality of a measured part.
 - How well the tolerances have been met
 - Using coordinates measured from the part surface
- Most measurements are made on a CMM but making measurements on the CNC has two advantages
 - Reduces time and costs by not requiring a CMM setup and programming
 - Enables on machine corrections before the machining is finished
- But in order to measure on the CNC we need a coordinate space
 - Machine tools operate in their own coordinate space
 - Designers and planners need the measurements in design or planning space

Design Space

- This is the coordinate system defined by the designer of the part
- He or she is the customer and the tolerances required by the customer must be met.



Planning space

- This is the coordinate space defined for the manufacturing solution
- Part is placed on a fixture in a virtual machine
 - For a multi-setup solution the part may be rotated to give better access to a feature
 - For a measured solution touch points may be planned in advance



Part on fixture Clamps holding part not shown As planned touch points shown

Machining space

- The CNC program executes in machine space
 - Post processor makes the coordinates
 - Operator sets offsets for actual position of part and actual length of tools



QIF and the Grand Challenge

- Results should be reported in design space
 - So the designer gets the data he or she wants, without regard to setup and machine configuration.
- New resources should be defined in planning space
 - To verify that new touch points are able to measure a surface
 - Planning space will be defined/managed by CNC NC program definitions, assisted by automated CMM measurement tools
- Measurements will take place in machine space
 - Touch points must be converted from machine space to design space
 - Digital twin supports all three options (design, planning and machine)

MTConnect results in planning space

QPID / UUID of face being measured

Locations and normals of contact points

fishhead20180123_5axis_mtc.log.bt - Notepad	
<u>F</u> ile <u>E</u> dit F <u>o</u> rmat <u>V</u> iew <u>H</u> elp	
2018-01-23T21:11:52.938Z pprogram fishhead 20180123 with asis	
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QIF Results in design space

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xml version="1.0" encoding="UTF-8"? - <qifdocument 1"="" xsi:schemalocation="http://qifstandards.org/xsd/qif3/QIFApplications/Q
- <Features>
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<pre></pre>		
<pre>- <filespec></filespec></pre>	Locations and normals of contac	<u>ct points</u>
Compensated > 10,255 a, 3,944 3, 3,94372 1,011544 5, 3,3445 3, 3,845481 1,013195 b, 9,75789 3,246411 1,009376 10,483557 3,093893 1,009774 11 7,554638 3,571633 0,835196 8,290460 3,459259 0,836021 9,01 5,334455 3,752286 0,665838 6,076524 3,700306 0,661856 6,81 10,483613 3,001087 0,662393 11,206610 2,829755 0,664155 4 8,290458 3,366185 0,488712 9,024810 3,245348 0,488055 9,77 Normals> 0,059280 0,96427 - 0,258364 0,077556 0,963016 - 0,251 - 0,255115 0,186660 0,948949 - 0,254270 0,204673 0,945478 - 0,255015 0,150454 0,954931 - 0 - 0,258364 0,077556 0,963016 - 0,2580 0,96427 - 0,258364 0,072556 0,150454 0,954931 - 0,255470 0,204673 0,945478 - 0,2553470 0,22614 0,941687 - 0 - 0,256545 0,150454 0,954931 - 0,255675 0,150454 0,95101 - 0,256545 0,150454 0,954931 - 0,255873 0,168585 0,952101 - 0 - 0,256545 0,150454 0,954931 - 0,255873 0,168585 0,952101 - 0 - 0,256545 0,150454 0,954931 - 0,255873 0,168585 0,952101 - 0 - 0,256545 0,150454 0,954931 - 0,255878 0,168585 0,952101 - 0 - 0,256545 0,150454 0,954931 - 0,255878 0,168585 0,952101 - 0 - 0,256545 0,150454 0,954931 - 0,255878 0,168585 0,952101 - 0 - 0,256545 0,150454 0,954931 - 0,255878 0,168585 0,952101 - 0 - 0,256545 0,150454 0,954931 - 0,255878 0,168585 0,952101 - 0 - 0,256545 0,150454 0,954931 - 0,255878 0,168585 0,952101 - 0 - 0,256545 0,150454 0,954931 - 0,255878 0,168585 0,952101 - 0 - 0,256545 0,150454 0,954931 - 0,255878 0,168585 0,952101 - 0 - 0,256545 0,150454 0,954931 - 0,255878 0,168585 0,952101 - 0 - 0,256545 0,150454 0,954931 - 0,255878 0,168585 0,952101 - 0 - 0,256545 0,150454 0,954931 - 0,255878 0,168585 0,95210 - 0,2565455 0,150454 0,954931 - 0,2558787 0,168585 0,95210 - 0 - 0,2565455 0,150454 0,954931 - 0,2558787 0,168585 0,95210 - 0	0.07052 5.795040 1.00903 6.810032 5.710292 1.009087 7.554038 3.018164 1.00885 2.06610 2.922817 1.011467 4.593544 3.857841 0.837688 5.334455 3.798817 0.83953 24815 3.338434 0.835360 9.755789 3.199880 0.835720 10.483583 3.047490 0.836084 16032 3.617230 0.662375 7.554638 3.525102 0.661540 8.290459 3.412718 0.662367 9 .593544 3.764779 0.490576 5.334455 3.705755 0.492227 6.076511 3.653636 0.48823 55787 3.106809 0.488411 10.483625 2.954613 0.488722 11.206610 2.783224 0.49049 8039 0.095820 0.961481 -0.257628 0.114063 0.959622 -0.257130 0.132278 0.957438 .255340 0.222614 0.941687 -0.252324 0.059280 0.964227 -0.258364 0.077556 0.9630 .255873 0.168855 0.952101 -0.255115 0.186660 0.948949 -0.254270 0.204673 0.9444 .257628 0.114063 0.959622 -0.257130 0.132278 0.957438 -0.256545 0.150454 0.9544 .2552324 0.059280 0.964227 -0.258364 0.077556 0.963016 -0.258039 0.095820 0.9614 .255115 0.186660 0.948949 -0.254270 0.204673 0.945478 -0.253340 0.222614 0.9416	2 6.290402 3.303600 1.009074 9.024817 3.384978 1.009013 9 6.076538 3.746977 0.8337875 6.816032 3.663761 0.836031 +11.206610 2.876286 0.837811 4.593544 3.811310 0.664232 9.024813 3.291891 0.661707 9.755789 3.153349 0.662064 86.816032 3.570699 0.488719 7.554638 3.478571 0.487884 19 9 //ts> - -0.256545 0.150454 0.954931 -0.255873 0.168585 0.952101 0.652632 0.95622 0.16 -0.258039 0.095820 0.961481 -0.257628 0.114063 0.959622 478 -0.253340 0.222614 0.941687 -0.252324 0.059280 0.964227 931 -0.255873 0.168585 0.952101 -0.255115 0.186660 0.948949 481 -0.257628 0.114063 0.959622 -0.257130 0.132278 0.957438 687 -0.252324 Normals>

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Digital Twin Framework

STEP Data

QIF Data

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File View Navigate Help \square	<u>File Edit Format View H</u> elp <characteristicnominalid>19</characteristicnominalid> <perpendicularitycharacteristicitem id="23"></perpendicularitycharacteristicitem>	^
FILE_SCHEMA (('AP242_MANAGED_MODEL_BASED_3D_ENGINEERING_MIM_LF { 1	<pre></pre>	
ANCHOR; <4210ed32-a599-43d1-9e84-96120d5ece42>=#983; /* perpendicularity_toler <767be10a-4d9a-49d8-9fd5-205adcd7ad82>=#987; /* perpendicularity_toler <459f7ee4-fced-4c3d-be7d-ca20f28e1855>=#991; /* perpendicularity_toler <a584e6fc-b7cc-4904-b41e-81c97383b15f>=#995; /* perpendicularity_toler <dc13594f-b8d5-4b23-bb38-ca86d96552e1>=#1094; /* datum_feature */ <9ce00c71-b207-4cb5-98fc-734ce92a60b0>=#1101; /* shape_aspect */ <9ffd7cbf-25bd-4be9-ab37-90b7ee855c69>=#1115; /* shape_aspect */ <754a586f-3593-4c1a-b0a9/a36f7c886540>=#1108; /* shape_aspect */</dc13594f-b8d5-4b23-bb38-ca86d96552e1></a584e6fc-b7cc-4904-b41e-81c97383b15f>	<pre></pre> <pre><</pre>	*
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S S	MTConnect Adapter Data	
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ijle <u>E</u> dit F <u>o</u> rmat <u>V</u> iew <u>H</u> elp		
2017-03-02T18:53:41.080Z pprogram BOXY_20170306 2017-03-02T13:53:49.104-05:00 measure feature:"dc13594f-b8d5-4b23-bb38-ca86d96552e1" order:1 2017-03-02T13:53:50.306-05:00 measure feature:"dc13594f-b8d5-4b23-bb38-ca86d96552e1" order:2 2017-03-02T13:53:51.507-05:00 measure feature:"dc13594f-b8d5-4b23-bb38-ca86d96552e1" order:3 2017-03-02T13:53:52.712-05:00 measure feature:"dc13594f-b8d5-4b23-bb38-ca86d96552e1" order:4 2017-03-02T13:53:53.913-05:00 measure feature:"dc13594f-b8d5-4b23-bb38-ca86d96552e1" order:5 2017-03-02T13:53:55.117-05:00 measure feature:"dc13594f-b8d5-4b23-bb38-ca86d96552e1" order:5	<pre>count:8 id:"FACE32373" characteristic:"3DLocation" x:-14.166667 y:-40.000000 z:9.166667 count:8 id:"FACE32373" characteristic:"3DLocation" x:-4.722222 y:-40.000000 z:9.166667 count:8 id:"FACE32373" characteristic:"3DLocation" x:4.722222 y:-40.000000 z:9.166667 count:8 id:"FACE32373" characteristic:"3DLocation" x:14.166667 y:-40.000000 z:9.166667 count:8 id:"FACE32373" characteristic:"3DLocation" x:-14.166667 y:-40.000000 z:73.33333 count:8 id:"FACE32373" characteristic:"3DLocation" x:-4.722222 y:-40.000000 z:73.33333</pre>	<

Digital Twin Measurement





Green good
Red bad
Yellow good and bad

Tablet, Phone or Large Screen TV